

Name: __Answers_____

ECEN 667

Exam #1

Thursday, October 17, 2017

75 Minutes

Closed book, closed notes
One 8.5 by 11 inch note sheet allowed
Calculators allowed

1. _____ / 24

2. _____ / 24

3. _____ / 28

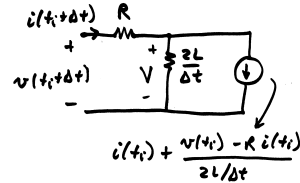
4. _____ / 24

Total _____ / 100

1. (20 points total)

Assume a 200Ω resistor is connected in series with a 0.1 H inductor and an open switch, and the series combination is connected to a voltage source of $v(t) = 1000\cos(2\pi 60t)$. If the switch is closed at time $t=0$, using the trapezoidal integration method with a time step of 0.0001 seconds, determine the current flowing in this series circuit at $t=0.0002$ seconds.

$$\frac{2L}{\Delta t} = \frac{0.2}{0.0001} = 2000, \text{ At } t = 0, i(0) = 0$$



At each time step we can get the current by superposition: the current just due to the terminal voltage plus the portion of the current source flowing into R (with terminal shorted), Which is $2000/2200 \times \text{current source} = 0.909$

$$\text{Current Source}(0.0001) = i(0) + \frac{v(0) - 200 \times i(0)}{2000} = 0.5 \text{ A}$$

$$i(0.0001) = \frac{v(0.0001)}{2200} + 0.909 \times \text{Current Source}(0.0001) = 999.3 / 2200 + 0.4545 = 0.909 \text{ A}$$

$$\text{Current Source}(0.0002) = i(0.0001) + \frac{v(0.0001) - 200 \times i(0.0001)}{2000} = 1.318 \text{ A}$$

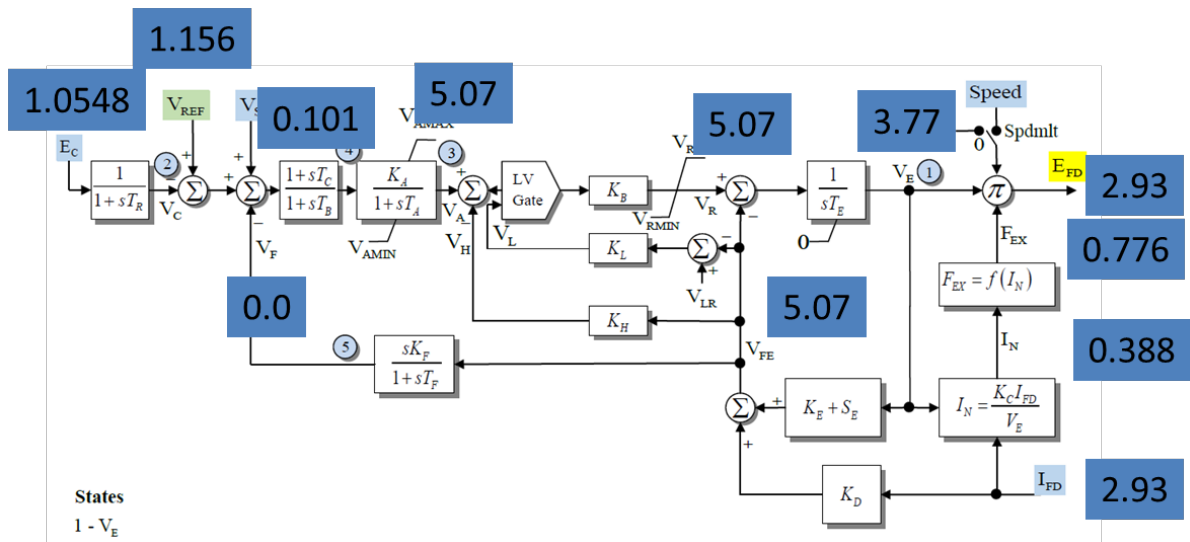
$$i(0.0002) = \frac{v(0.0002)}{2200} + 0.909 \times \text{Current Source}(0.0002) = 997.2 / 2200 + 1.199 = 1.652 \text{ A}$$

2. (24 points total)

For the EXAC2 exciter model shown below, assume that the initial conditions are $E_{FD}=2.93$, $I_{FD} = 2.93$, and the exciter's input is the terminal voltage of 1.0548 pu. For parameters assume is $T_R=0.05$, $T_C=1$, $T_B=2$, $K_A=50$, $T_A=0.1$, $K_B=1$, $K_L=1$, $V_{LR}=10$, $T_E=0.1$, $K_H=0$, $K_E=1$, $K_D=0$, $T_F=1.2$, $K_F=0.02$, $K_C=0.5$. The saturation values are $S_E(2.5) = 0.02$, and $S_E(3.0) = 0.1$. Hence for a saturation function assume $S_E(V_E) = 0.1222 \times (V_E - 2.095)^2$.

Determine the initial value for V_{REF} where $V_{ERR} = V_{REF} - V_T$; (you may assume $V_s=0$)

To simplify the problem you may assume that for the initial I_N value $f(I_N)$ can be approximated as being on the segment with $F_{EX} = 1 - 0.577 * K_C * I_{FD} / V_E$.



3. (28 points total) (True/false)

Two points each. Circle T if statement is true, F if statement is False.

- T F 1. With the GENROU model we always have $X_d'' = X_q''$.
- T F 2. Explicit numerical integration methods have the advantage of always being numerically stable.
- T F 3. In EMTP analysis much of the system can be treated as decoupled because of the transmission line propagation delays.
- T F 4. In transient stability the stator transients are typically ignored.
- T F 5. When converting synchronous machine models to per unit the time constants are independent of the assumed MVA base.
- T F 6. In contrast to EMTP applications, transient stability applications require a slack bus to insure total generation is always equal to total load plus losses
- T F 7. With salient pole machines saturation is often ignored on the direct axis because of its relatively large air gap compared to the quadrature axis.
- T F 8. When using Carson's method to determine the inductance of untransposed multi-phase transmission lines, the inductance is independent of the ground resistivity.
- T F 9. While perhaps interesting from a theoretical perspective, machine magnetic saturation is seldom encountered in practice.
- T F 10. There is not a unique way to implement non-windup limits for a lead-lag block.
- T F 11. Compensation can be used to allow an exciter to regulate a voltage other than its terminal voltage.
- T F 12. Per unit values are always dimensionless.
- T F 13. In a large interconnection, such as the Eastern Interconnect, in the first few seconds following a generator loss contingency the frequencies at the buses in the system can vary from each other.
- T F 14. While one of the oldest synchronous machine models, the classical model is still widely used in commercial transient stability studies in North America.

4. (24 points total)

A 60 Hz generator is supplying 400 MW and 0 Mvar to an infinite bus (measured at the infinite bus) with 1.0 per unit voltage at the infinite bus through two parallel transmission lines. Each transmission line has a per unit impedance (100 MVA base) of $0.09j$. The per unit transient reactance for the generator is $0.0375j$ (on a 100 MVA base), the per unit inertia constant for the generator (H) is 10 seconds, and damping is 0 per unit.

At time = 0 one of the transmission lines experiences a balanced three phase short to ground one third ($1/3$) of the way down the line from the generator to the infinite bus (i.e., model the line with $1/3$ its original impedance on the generator side and $2/3$ on the infinite bus side).

- Using the classical generator model discussed in class (constant voltage behind transient reactance), determine the prefault internal voltage magnitude and angle of the generator.
- Express the system dynamics during the fault as a set of first order differential equations.
- Using a second order Runge-Kutta method, determine the generator internal angle at the end of the second time step. Use a time step of 0.02 seconds.

Solution

$$a) \quad \bar{E} = 1.0 + (j0.045 + j0.0375)(4.0) = 1 + j0.33 = 1.053 \angle 18.26^\circ$$

$$b) \quad \text{During the fault } V_{th} = 0.25, Z_{th} = j0.0225$$

$$\frac{d\delta}{dt} = \Delta\omega_{pu} \omega_s = \Delta\omega_{pu} (377)$$

$$\frac{d\Delta\omega_{pu}}{dt} = \frac{1}{2H} (P_M - P_E) = \frac{1}{20} \left(4 - \frac{1.053 \times 0.25}{0.0225 + 0.0375} \sin \delta \right) = 0.2 - 0.22 \sin \delta \quad (\text{during the fault})$$

$$c) \quad \mathbf{x} = \begin{bmatrix} \delta \\ \Delta\omega_{pu} \end{bmatrix}, \quad \mathbf{x}(0) = \begin{bmatrix} 0.3187 \\ 0 \end{bmatrix}, \quad \Delta t = 0.01$$

$$\mathbf{x}(t + \Delta t) = \mathbf{x}(t) + \frac{1}{2}(\mathbf{k}_1 + \mathbf{k}_2) \quad \text{with } \mathbf{k}_1 = \Delta \mathbf{f}(\mathbf{x}(t)), \mathbf{k}_2 = \Delta \mathbf{f}(\mathbf{x}(t) + \mathbf{k}_1),$$

$$\mathbf{k}_1(0.0) = \begin{bmatrix} 0 \\ 0.0026 \end{bmatrix}, \mathbf{k}_2(0.0) = \begin{bmatrix} 0.0198 \\ 0.0026 \end{bmatrix} \rightarrow \mathbf{x}(0.02) = \begin{bmatrix} 0.3286 \\ 0.0026 \end{bmatrix} \rightarrow 18.82^\circ$$

$$\mathbf{k}_1(0.02) = \begin{bmatrix} 0.0196 \\ 0.0026 \end{bmatrix}, \mathbf{k}_2(0.02) = \begin{bmatrix} 0.0392 \\ 0.0025 \end{bmatrix} \rightarrow \mathbf{x}(0.04) = \begin{bmatrix} 0.3580 \\ 0.0052 \end{bmatrix} \rightarrow 20.51^\circ$$